Towards Self-Assembling Artificial Neural Networks through Neural Developmental Programs

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Background: Indirect encoding

Compress large Neural Networks.

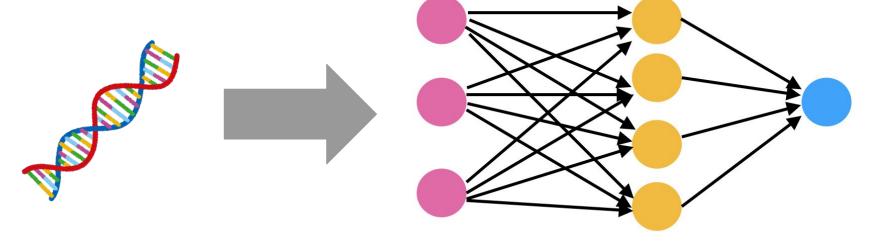
HyperNEAT: describe connection of neuron by function. when connection is repeated, the information can be smaller

Background: Developmental Encoding

Similar to Indirect encoding.

Grow the Neural Network from the gene (same gene for all nodes)

poor performance, not researched





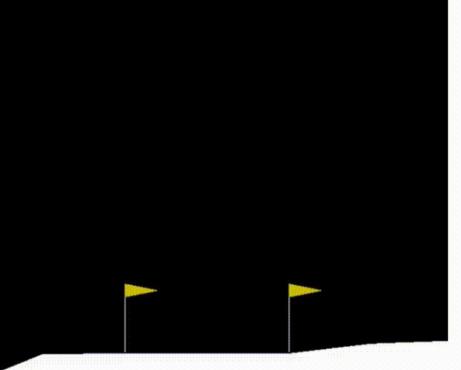
Achieve high performance with Developmental Neural Network in various environment

Traditional method: Grow regardless current Network state

New approach: adapt the growth rule to suit task

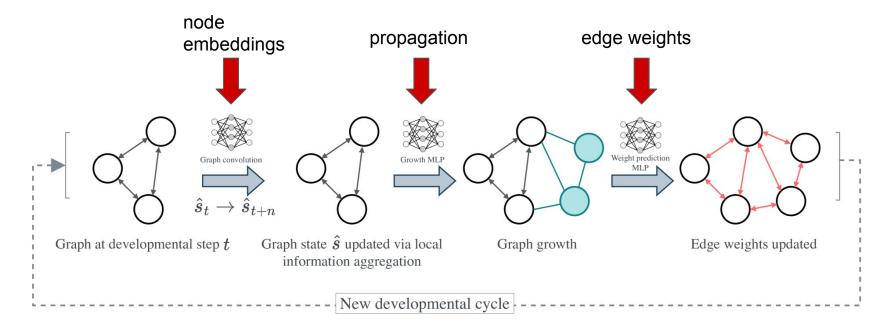
Growth cycle: 0, Graph si





Cycle of NDP (Neural Developmental Program)

NDP is 3 types of MLP (Multi-Layer Perceptron)



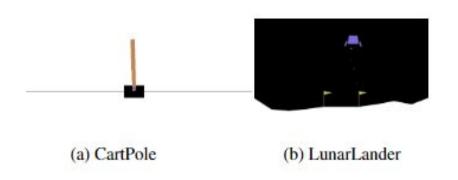
NDP (Neural Developmental Program)

- Evolutionary-based
 - easily explore different architectures without having to worry about their differentiability

- Gradient-based
 - sample efficient, allow scaling to higher dimensions offline reinforcement learning.

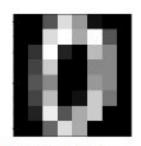
Experiments

- continuous/discrete action tasks
- classification





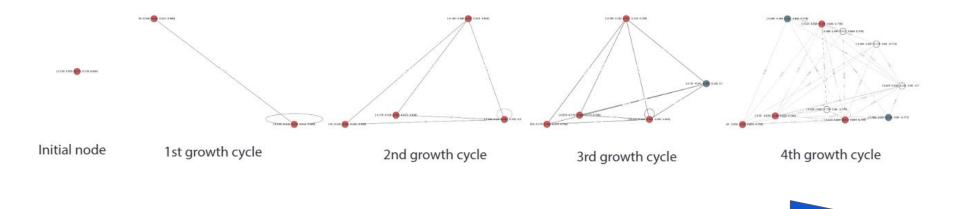
(c) HalfCheetah



(d) 8x8 MNIST Example

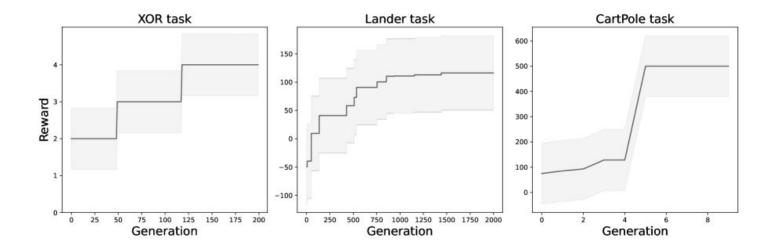
Results: Evolutionary-based

CartPole training results



Results: Evolutionary-based

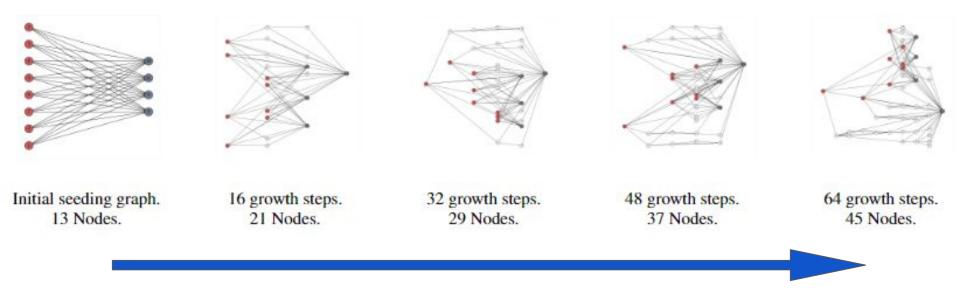
Evolutionary-based training results



Results: Gradient-based

Growth of NN for Lunar Lander task.

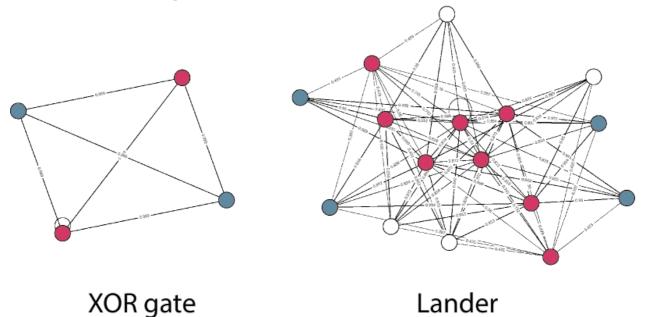
Gradient-based performed better when initialized by fully-connected input/output



Results: Gradient-based

Reaches comparable performance to the evolutionary-based

Deteriorate after certain growth steps



Discussion & Future work

Unlike Developmental Encoding in related research, NDP required more information than the resulting network. However, this is not a problem as the focus is on performance.

Add activity-dependent growth like biological systems

Thank you for your attention.